

Overview

Problem: how to split the transportation task in order to obtain an equitable and optimal transportation strategy between multiple agents ?

Contributions:

- We introduce **EOT** (Equitable and Optimal Transport) and show that it solves a *fair division problem* where heterogeneous resources have to be shared among *multiple agents*.
- We derive its dual and prove *strong duality* results. As a by-product, we show that EOT is related to some usual IPMs families and in particular the widely known *Dudley metric*.
- We propose an *entropic regularized version* of the problem, derive its dual formulation, obtain strong duality. We then derive an *efficient algorithm* to compute it.
- We propose other applications of EOT for *Operations Research problems*.

Primal Formulation

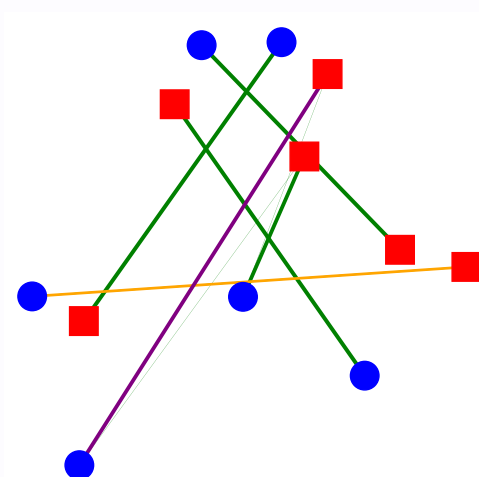
Distributions: $\mu \in \mathcal{M}_1^+(\mathcal{X})$ and $\nu \in \mathcal{M}_1^+(\mathcal{Y})$

Cost/Utility functions : $c_i : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$ for $i \in \{1, \dots, N\}$

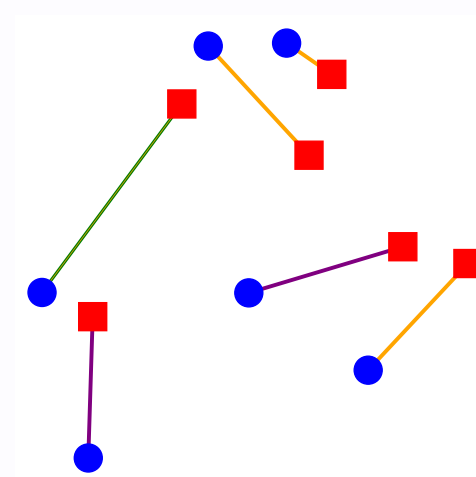
Couplings: $\Gamma_{\mu, \nu}^N := \left\{ (\gamma_i)_{i=1}^N \text{ s.t. } \Pi_{1\#} \sum_{i=1}^N \gamma_i = \mu, \Pi_{2\#} \sum_{i=1}^N \gamma_i = \nu \right\}$

Definition of Equitable and Optimal Transport

$$\text{EOT}_c(\mu, \nu) := \inf_{(\gamma_i)_{i=1}^N \in \Gamma_{\mu, \nu}^N} \max_{i \in \{1, \dots, N\}} \int c_i(x, y) d\gamma_i(x, y).$$



Utility functions:
 $\forall i, c_i < 0$



Cost functions:
 $\forall i, c_i \geq 0$

Equitable and Optimal

- The division of the transportation task is **equitable**:

Proposition

If the cost/utility functions are of constant sign then we have

$$\text{EOT}_c(\mu, \nu) = \min_{(\gamma_i)_{i=1}^N \in \Gamma_{\mu, \nu}^N} \left\{ t \text{ s.t. } \forall i \in \{1, \dots, N\} \int c_i(x, y) d\gamma_i(x, y) = t \right\}$$

- The division of the transportation task is **optimal**:

Proposition

If the cost/utility functions are of constant sign then for any $(\gamma_i^*)_{i=1}^N \in \Gamma_{\mu, \nu}^N$ solution of EOT, we have for all $i \in \{1, \dots, N\}$:

$$\gamma_i^* \in \operatorname{argmin}_{\gamma \in \Gamma_{\mu_i^*, \nu_i^*}^1} \int c_i d\gamma \text{ where } \mu_i^* := \Pi_{1\#} \gamma_i^*, \nu_i^* := \Pi_{2\#} \gamma_i^*$$

Applications:

EOT solves a relaxation of the **fair cake-cutting** problem.

Dual Formulation

Dual space:

$$\mathcal{F}_c^\lambda := \{(f, g) \in \mathcal{C}^b(\mathcal{X}) \times \mathcal{C}^b(\mathcal{Y}) \text{ s.t. } \forall i \in \{1, \dots, N\}, f \oplus g \leq \lambda c_i\}$$

Strong duality holds: $\text{EOT}_c(\mu, \nu) = \sup_{\lambda \in \Delta_N^+} \int f d\mu + \int g d\nu$
 $(f, g) \in \mathcal{F}_c^\lambda$

Link with other Probability Metrics:

- Optimal Transport: if $N = 1$, $\text{EOT}_c(\mu, \nu) = W_c(\mu, \nu)$
- Dudley Metric: if $c_1 = d$ and $c_2 = 2 \times \mathbf{1}_{x \neq y}$,

$$\text{EOT}_c(\mu, \nu) = \sup_{f \in B_d(\mathcal{X})} \int f d\mu - \int f d\nu$$

$$B_d(\mathcal{X}) := \left\{ f \in C^b(\mathcal{X}) : \|f\|_\infty + \|f\|_{\text{lip}} \leq 1 \right\}$$

Entropic Relaxation

KL divergence: $\text{KL}(\mu || \nu) = \int \log \frac{d\mu}{d\nu} d\mu + \int d\nu - \int d\mu$

Definition of the entropic version of EOT:

$$\text{EOT}_c^\epsilon(\mu, \nu) := \inf_{(\gamma_i)_{i=1}^N \in \Gamma_{\mu, \nu}^N} \max_{i \in \{1, \dots, N\}} \int c_i(x, y) d\gamma_i(x, y) + \epsilon \sum_{j=1}^N \text{KL}(\gamma_j || \mu \otimes \nu)$$

Strong duality holds:

$$\text{EOT}_c^\epsilon(\mu, \nu) = \sup_{\lambda \in \Delta_N^+} \sup_{f \in \mathcal{C}_b(\mathcal{X})} \int f d\mu + \int g d\nu$$

$$g \in \mathcal{C}_b(\mathcal{Y})$$

$$- \epsilon \sum_{i=1}^N \left(\int e^{\frac{f(x) + g(y) - \lambda_i c_i(x, y)}{\epsilon}} d\mu(x) d\nu(y) - 1 \right)$$

Projected Sinkhorn Algorithm

Algorithm 1 Projected Alternating Maximization

Input: $\mathbf{C} = (C_i)_{1 \leq i \leq N}$, $a, b, \epsilon, L_\lambda$

Init: $f^0 \leftarrow \mathbf{1}_n$; $g^0 \leftarrow \mathbf{1}_m$; $\lambda^0 \leftarrow (1/N, \dots, 1/N) \in \mathbb{R}^N$

for $k = 1, 2, \dots$ **do**

$$K^k \leftarrow \sum_{i=1}^N K_i^{\lambda^{k-1}}$$

$$c_k \leftarrow \langle f^{k-1}, K^k g^{k-1} \rangle, f^k \leftarrow \frac{c_k a}{K^k g^{k-1}}$$

$$d_k \leftarrow \langle f^k, K^k g^{k-1} \rangle, g^k \leftarrow \frac{d_k b}{(K^k)^T f^k}$$

$$\lambda^k \leftarrow \text{Proj}_{\Delta_N^+} \left(\lambda^{k-1} + \frac{1}{L_\lambda} \nabla_\lambda F_{\mathbf{C}}^\epsilon(\lambda^{k-1}, f^k, g^k) \right).$$

end

Result: λ, f, g

Operations Research

- Minimal transportation time
- Sequential optimal transport